

Generation of Low-Discrepancy Point Sets and Sequences via LLM Evolutionary Search

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Abstract

Low-discrepancy point sets and sequences are foundational to quasi-Monte Carlo (QMC) methods, which are indispensable in fields requiring high-dimensional integration, such as financial engineering, computer graphics, and computational physics. This paper utilizes a Large Language Model (LLM) within an evolutionary search paradigm, inspired by the principles of systems such as AlphaEvolve, on two significant, long-standing problems. First, we apply the framework to find 2D and 3D point sets with minimal star discrepancy. Our method not only rediscovers known optimal configurations for small point sets but also establishes new state-of-the-art for larger 2D point sets ($N \geq 30$) and provides the first known constructions for 3D point sets for $N > 8$. Second, by evolving the constituent direction numbers for Sobol' sequences, our method discovers new parameter sets that significantly reduce randomized QMC integration error for pricing a variety of 32-dimensional exotic options, outperforming established, widely-used direction numbers. These results highlight the potential of LLM-driven evolutionary algorithms as a powerful tool for automated discovery in computational mathematics. Data and code are available at <https://github.com/hockeyguy123/openevolve-star-discrepancy>.

Introduction

Numerical integration in high dimensions is a cornerstone of modern science and engineering. While standard Monte Carlo (MC) methods offer a robust approach, their convergence rate, governed by the Central Limit Theorem, is often insufficient for applications requiring high precision (Glasserman 2003). Quasi-Monte Carlo (QMC) methods provide a compelling alternative by replacing pseudorandom samples with deterministic, highly uniform point sets (Dick and Pillichshammer 2010; Owen 1995). The uniformity of these sets is quantified by their discrepancy, with lower values corresponding to more evenly distributed points. The Koksma-Hlawka inequality provides the theoretical underpinning for QMC, guaranteeing that the integration error is bounded by the product of the variation of the integrand and the star discrepancy of the point set (Koksma 1964; Hlawka 1961).

This relationship has fueled decades of research into the discovery and construction of low-discrepancy sets. A pri-

mary challenge in this field is the "ab initio" construction of a finite point set of N points in d dimensions that minimizes star discrepancy. This is a problem of combinatorial complexity, and while optimal solutions have been found in 2D for $N \leq 21$ and in 3D for $N \leq 8$ (Clément et al. 2024), the problem remains largely open for larger N and higher dimensions.

A related challenge is the construction of infinite low-discrepancy sequences, such as those by Halton, Hammerley, and Sobol'. Among these, Sobol' sequences are particularly prominent due to their excellent distribution properties and efficient generation (Sobol' 1967). However, their quality is highly dependent on a set of integer parameters known as direction numbers, and finding optimal parameters that ensure uniformity across all low-dimensional projections is a difficult combinatorial search problem (Joe and Kuo 2008).

Recent breakthroughs in Large Language Models (LLMs) have demonstrated their remarkable capabilities in code generation, logical reasoning, and pattern recognition (Gemini Team et al. 2025). This has motivated the development of automated scientific discovery systems, such as AlphaEvolve, which leverage LLMs to navigate complex search spaces (Novikov et al. 2025). In this work, we utilize the OpenEvolve framework (Sharma 2025), an open-source implementation based on the principles of AlphaEvolve, to tackle the aforementioned challenges in discrepancy theory. We treat the construction of these mathematical objects as a program synthesis problem within an evolutionary framework (Koza 1994). The LLM acts as an intelligent mutation operator, iteratively modifying code that generates candidate solutions based on feedback from a fitness function.

This paper presents the successful application of this LLM-driven evolutionary approach to two fundamental problems:

1. Discovering finite 2D and 3D point sets with state-of-the-art low star discrepancy.
2. Searching for superior Sobol' direction numbers to minimize randomized quasi-Monte Carlo (rQMC) integration error in the high-dimensional context of pricing exotic financial options (Paskov and Traub 1995).

Our results show that this methodology can match and, in several important cases, surpass the best known human-

derived solutions. This suggests that LLM-driven evolutionary search is a promising new paradigm for exploration and discovery in computational mathematics.

Theoretical Background

Star Discrepancy

Star discrepancy is the most common measure for quantifying the uniformity of a point set within the d -dimensional unit hypercube, $[0, 1]^d$ (Owen 1995). It captures the largest deviation between the volume of an axis-aligned "anchor box" and the fraction of points contained within it.

Definition 1 (Star Discrepancy). Let $P = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ be a set of N points in $[0, 1]^d$. An anchor box $[\mathbf{0}, \mathbf{q}]$ for any $\mathbf{q} = (q_1, \dots, q_d) \in [0, 1]^d$ is the hyperrectangle $[0, q_1) \times \dots \times [0, q_d)$. The star discrepancy D_N^* of the set P is defined as:

$$D_N^*(P) = \sup_{\mathbf{q} \in [0, 1]^d} \left| \frac{\#(P \cap [\mathbf{0}, \mathbf{q}])}{N} - \text{Vol}([\mathbf{0}, \mathbf{q}]) \right| \quad (1)$$

Here, the supremum is taken over all possible anchor boxes. A small D_N^* value implies that for any anchor box, the fraction of points falling within it is a good approximation of its volume, indicating high uniformity. The practical importance of star discrepancy is cemented by the Koksma-Hlawka inequality (Koksma 1964; Hlawka 1961), which bounds the error of QMC integration:

$$\left| \int_{[0, 1]^d} f(\mathbf{u}) d\mathbf{u} - \frac{1}{N} \sum_{i=1}^N f(\mathbf{x}_i) \right| \leq V(f) \cdot D_N^*(P) \quad (2)$$

where $V(f)$ is the total variation of the function f in the sense of Hardy and Krause. This inequality guarantees that point sets with lower star discrepancy lead to smaller integration error bounds.

Sobol Sequences and Direction Numbers

Sobol' sequences are a class of low-discrepancy sequences that are particularly effective for QMC integration (Sobol' 1967; Dick and Pillichshammer 2010). They are constructed using the properties of primitive polynomials over the finite field of two elements, \mathbb{F}_2 .

Definition 2 (Sobol' Sequence Construction). For each dimension $j \geq 1$, a primitive polynomial over \mathbb{F}_2 of degree s_j is chosen (Dick and Pillichshammer 2010):

$$P_j(z) = z^{s_j} + a_{1,j}z^{s_j-1} + \dots + a_{s_j-1,j}z + 1 \quad (3)$$

where the coefficients $a_{k,j}$ are either 0 or 1. From this polynomial, a sequence of positive, odd integers called direction numbers $m_{k,j}$ (for $k = 1, \dots, s_j$) are chosen freely. Subsequent direction numbers ($k > s_j$) are generated via the recurrence relation:

$$m_{k,j} = 2a_{1,j}m_{k-1,j} \oplus \dots \oplus 2^{s_j}m_{k-s_j,j} \oplus m_{k-s_j,j} \quad (4)$$

where \oplus denotes the bitwise XOR operation. These integers are converted into direction vectors $v_{k,j}$ by $v_{k,j} = m_{k,j}/2^k$.

The j -th coordinate of the i -th point in the sequence, $x_{i,j}$, is then generated by:

$$x_{i,j} = i_1 v_{1,j} \oplus i_2 v_{2,j} \oplus \dots \quad (5)$$

where $(\dots i_2 i_1)_2$ is the binary representation of the index i . The quality of the Sobol' sequence, particularly the uniformity of its low-dimensional projections, is critically dependent on the choice of the primitive polynomials and the initial direction numbers (m_1, \dots, m_s) . The work of Joe and Kuo (2008) provides a widely used set of these parameters that serve as a strong baseline.

Related Work

The challenge of constructing low-discrepancy sets has been approached from multiple angles, ranging from classical number theory to modern machine learning. Our work builds upon these diverse foundations.

Classical approaches for generating low-discrepancy sets are primarily number-theoretic. Foundational methods include Halton, Hammersley, and Sobol' sequences, which are designed to achieve superior asymptotic uniformity compared to random sampling (Rusch et al. 2024; Clément et al. 2024). While powerful, these classical constructions are not always optimal for a finite number of points N . To address this, other works formulate the search for optimal finite point sets as a direct optimization problem. Mathematical programming has been used to find provably optimal sets, though these approaches are computationally intensive and limited to small instances (Clément et al. 2024). Heuristic methods, such as genetic algorithms and threshold accepting, have been applied to tackle larger instances by searching the space of point configurations (Clément et al. 2023).

More recently, machine learning techniques have been introduced to this domain. Message-Passing Monte Carlo (MPMC) leverages Graph Neural Networks (GNNs) to transform random initial points into low-discrepancy configurations, achieving state-of-the-art results by directly optimizing point coordinates (Rusch et al. 2024). Our work differs by framing the task as a program synthesis problem rather than direct coordinate optimization.

A related line of research focuses on optimizing the parameters of Sobol' sequences. The quality of a Sobol' sequence is critically dependent on a set of initialization parameters known as direction numbers. The direction numbers published by Joe and Kuo (2008) are a widely-used standard, derived from an extensive computational search to find parameters that ensure high uniformity in two-dimensional projections by minimizing a quality measure known as the t -value. Subsequent work has focused on further improving these parameters or guaranteeing quality for specific projection properties crucial for applications such as computer graphics (Bonneel et al. 2025).

Our approach is most closely related to the emerging paradigm of using Large Language Models (LLMs) for automated scientific discovery. Novikov et al. (2025) introduces AlphaEvolve, a framework that combines LLMs with an evolutionary search, treating algorithm discovery as a program evolution problem where the LLM functions as an intelligent mutation operator and receives feedback from a

fitness function. This method has successfully discovered novel algorithms for fundamental problems, from matrix multiplication (Fawzi et al. 2022) to open mathematical conjectures (Romera-Paredes et al. 2024). Our work is directly inspired by these principles, applying a similar evolutionary loop to the specific mathematical challenges of discovering low-discrepancy sets and optimizing Sobol’ sequences.

Methodology

We consider two related quasi–Monte Carlo design problems. First, we seek finite point sets of size N in $[0, 1]^d$ with small star discrepancy for $d \in \{2, 3\}$. Second, we aim to choose Sobol’ direction numbers that reduce the integration error of a randomized QMC estimator for a 32-dimensional Asian option pricing problem. Both problems can be viewed as searching over programs that generate either a point set or a digital sequence. Our method instantiates this search via an evolutionary program synthesis framework in which a large language model (LLM) repeatedly rewrites Python code snippets that produce candidate constructions; the quality of the resulting constructions, measured by task-specific fitness functions, then guides subsequent mutations.

Our approach is based on the OpenEvolve framework, an open-source implementation of the principles demonstrated by AlphaEvolve (Novikov et al. 2025). It frames the search for novel mathematical constructs as an evolutionary search over a population of programs that generate them (Koza 1994). The LLM serves as a sophisticated mutation operator, guided by a task-specific fitness function.

The evolutionary loop (Romera-Paredes et al. 2024) proceeds as follows:

1. **Initialization:** The process begins with a population of “parent” programs. These programs are code snippets in Python that generate a candidate solution. The initial population can be seeded with simple heuristics or well-known constructions.
2. **Evaluation:** Each program in the population is executed, and its output is evaluated by a fitness function. The fitness function returns a scalar score quantifying the quality of the solution (e.g., lower rQMC MSE or star discrepancy is better).
3. **Selection and Prompting:** High-performing programs are selected to serve as parents. A detailed prompt is then constructed for the LLM, including the parent program’s source code, its fitness score, and an instruction tasking the LLM with generating a variation that will improve upon the score. The prompt also includes code from other high-performing “inspirations” to encourage crossover as well as guidance from the user (Appendix B).
4. **Generation (Mutation):** The LLM receives the prompt and generates a new, modified program. This is the core mutation step. The LLM’s ability to understand code syntax and semantics allows for complex and structured modifications.
5. **Loop:** The newly generated program is evaluated, its fitness is scored, and it is added to the population. The process then repeats, iteratively refining the population toward better solutions.

Experimental Setup

We maintained a total population of 60 candidate programs with four islands to encourage the development of diverse solutions and prevent premature convergence. In addition to the islands, a MAP-Elites-style archive stored the top 25 elite programs discovered during the run, preserving high-performing solutions. In each generation, a parent program was selected for mutation: with a 70% probability, the parent was chosen from the high-performing archive.

The mutation operator itself was a Large Language Model (Google’s Gemini 2.0 Flash) (Gemini Team et al. 2025), which was instructed to perform a complete rewrite of the core program functions. To provide a rich context for this mutation, the LLM prompt included not only the parent program but also the source code of the three top-performing “inspiration” programs from the database, serving as a form of multi-parent inspiration or crossover. We set the LLM’s temperature to 0.7 and top- p to 0.95.

Each evolutionary run involved approximately 2000 LLM API calls and took roughly 96 hours to complete. This corresponds to on the order of three minutes per mutation–evaluation cycle. The dominant computational cost is the repeated evaluation of the fitness functions: computing star discrepancy for the point-set tasks and running the rQMC estimator with many randomizations for the Sobol’ task. LLM inference time is comparatively small because we use a hosted API and relatively short prompts.

The experiments were conducted on a workstation equipped with an AMD EPYC 7763 CPU and 64 GB of RAM. Due to computational constraints, no automated hyperparameter optimization was performed and only one evolutionary run per problem was conducted.

Hyperparameter choices. The evolutionary hyperparameters were chosen to balance diversity and computational budget. A population of 60 programs distributed across four islands provided enough diversity to avoid premature convergence while keeping evaluation costs manageable. The archive size of 25 and the 70% probability of selecting parents from the archive bias the search toward exploiting high-performing programs while still allowing exploration via the remaining island-based sampling. For the LLM, the temperature of 0.7 and top- p of 0.95 are standard settings for code generation that encourage non-trivial mutations without producing overly noisy outputs. Once selected, the same configuration was used for all experiments to provide a consistent comparison across tasks.

Code, generated point sets, and Sobol’ parameters are available at <https://github.com/hockeyguy123/openevolve-star-discrepancy>.

Discovery of Low-Discrepancy Point Sets

A two-phase strategy was employed to balance broad exploration with fine-tuned optimization.

- **Phase 1: Direct construction.** The LLM was prompted to generate Python code that directly constructs an N -point set in a d -dimensional space. The initial parent program in 2D implemented a simple shifted Fibonacci lattice (Listing 1) and in 3D implemented a scrambled

Listing 1: Initial program for 2D point-set search.

```

1 def construct_star():
2     A = np.zeros((N, 2))
3     phi = (math.sqrt(5) - 1) / 2
4     for i in range(N):
5         A[i, 0] = (i + 0.5) / N
6         A[i, 1] = ((i * phi) % 1 + (0.5
7                     / N)) % 1
8     return A

```

Listing 2: Initial program for 3D point-set search.

```

1 def construct_star():
2     A = Sobol(d=3, scramble=True, seed
3              =42).random(n=N)
4     return A

```

Sobol’ sequence (Listing 2). This phase encouraged the LLM to explore a wide range of constructive heuristics.

- **Phase 2: Iterative optimization.** After a sufficient number of iterations, the LLM was prompted to generate Python code that uses iterative optimization routines (e.g., `scipy.optimize.minimize`) to refine an initial guess. This shifted the search from finding explicit constructions to a direct optimization of the point coordinates.
- **Fitness function.** The fitness score was $\frac{1}{1+D_N^*}$, where D_N^* is the star discrepancy of the generated point set.

Discovery of Sobol’ Direction Numbers

- **Program representation.** The evolved programs are Python functions that return a list of dictionaries. Each dictionary contains the Sobol’ parameters (`s`, `a`, `m_i`) for a single dimension.
- **Initialization.** The initial population contains the standard implementation of the direction numbers (Joe and Kuo 2008).
- **Fitness function.** The primary fitness metric is $\frac{1}{1+\text{MSE}}$, where MSE is the mean squared error of an rQMC estimate for a 32-dimensional Asian option price. The MSE is calculated for $N = 8192$ points and averaged over 1000 consistent randomizations (left-matrix scramble followed by a Cranley–Patterson random shift, i.e., LMS+shift) to ensure robustness and reproducibility.

Experiments and Results

Listing 3: Directly Constructed 16 Point Set ($N = 16$)

```

1 def construct_star():
2     A = np.zeros((N, 2))
3     phi=(math.sqrt(5)-1)/2
4     for i in range(N):
5         A[i, 0]=(i+(1/math.sqrt(3)))/N
6         A[i, 1]=((0.5+(i*phi)%1))%1
7     return A

```

N	Fibonacci	MPMC	LLM	Clément et al.
1	1.0000	0.6180	0.6180	0.6180
2	0.6909	0.3660	0.3660	0.3660
3	0.5880	0.2847	0.2847	0.2847
4	0.4910	0.2500	0.2500	0.2500
5	0.3528	0.2000	0.2000	0.2000
6	0.3183	0.1692	0.1667	0.1667
7	0.2728	0.1508	0.1500	0.1500
8	0.2553	0.1354	0.1328	0.1328
9	0.2270	0.1240	0.1235	0.1235
10	0.2042	0.1124	0.1111	0.1111
11	0.1857	0.1058	0.1039	0.1030
12	0.1702	0.0975	0.0960	0.0952
13	0.1571	0.0908	0.0892	0.0889
14	0.1459	0.0853	0.0844	0.0837
15	0.1390	0.0794	0.0791	0.0782
16	0.1486	0.0768	0.0745	0.0739
17	0.1398	0.0731	0.0712	0.0699
18	0.1320	0.0699	0.0676	0.0666
19	0.1251	0.0668	0.0654	0.0634
20	0.1188	0.0640	0.0611	0.0604
30	0.0792	N/A	0.0438	0.0424
40	0.0638	N/A	0.0331	0.0332
50	0.0531	N/A	0.0278	0.0280
60	0.0442	0.0273	0.0234	0.0244
100	0.0275	0.0188	0.0150	0.0193

Table 1: 2D Star Discrepancy Comparison for $N = 1...100$ between Fibonacci, MPMC (Message-Passing Monte Carlo), LLM evolutionary search, and Clément et al. (provably optimal for $N \leq 20$). Best values are **bolded**.

Discovery of Low-Discrepancy Point Sets

We first applied our two-phase strategy to the canonical problem of discovering N -point sets in 2D and 3D with minimal star discrepancy. We illustrate the discovery process for a 2D, 16-point set (Fig. 1). The initial program, a Fibonacci lattice (Listing 1), had a discrepancy of 0.0962. After 243 iterations in the direct construction phase, a new construction was found with a discrepancy of 0.0924 (Listing 3), which consisted of fine-tuning optimal shifts to the Fibonacci lattice. After switching to the iterative optimization phase, the framework further refined the point set, achieving a final discrepancy of 0.0744, which is within 0.68% of the known optimal value of 0.0739. The final program creates an initial guess, consisting of a randomly jittered Fibonacci lattice, followed by a SLSQP optimization loop with stochastic restarts (Listing 4).

We then benchmarked our method against Fibonacci, MPMC (Rusch et al. 2024), and known optimal point sets (Clément et al. 2024) for $N = 1...100$ (Table 1). Our method successfully rediscovers the known optimal point sets for $N \leq 10$ and remains highly competitive for larger N . The most significant results came from searching for larger point sets where optimal solutions are not known. For 2D point sets with $N > 30$, LLM evolutionary search discovered new configurations with lower star discrepancy than the best-known values from the literature. For instance, for $N = 100$, our method found a point set with a discrepancy of 0.0150,

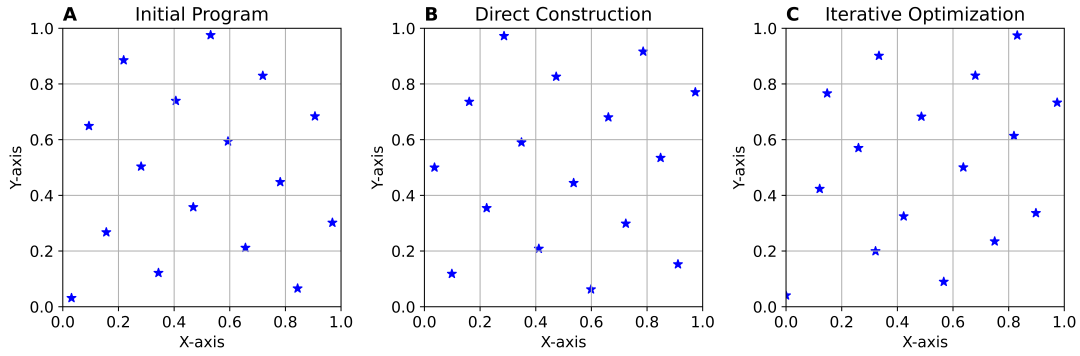


Figure 1: Visualization of $N = 16$ point set generation in two dimensions. (A) Initial shifted Fibonacci lattice (Discrepancy: 0.0962). (B) Best direct construction found in Phase 1 (Discrepancy: 0.0924). (C) Final optimized point set from Phase 2 (Discrepancy: 0.0744), which is within 0.68% of the known optimal value of 0.0739.

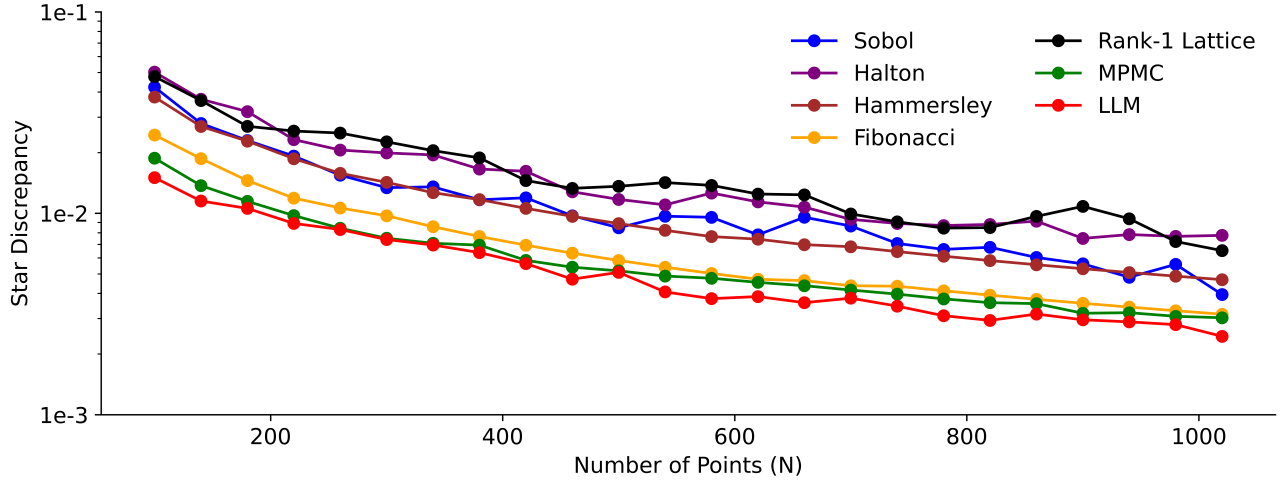


Figure 2: The Star Discrepancy D_N^* of Sobol', Halton, Hammersley, Fibonacci, Rank-1-Lattice, MPMC (message passing Monte Carlo), and LLM evolutionary search sequences for increasing number of points $N = 100 \dots 1020$ in 2D.

N	MPMC	LLM	Clément et al.
1	0.6833	0.6823	0.6823
2	0.4239	0.4239	0.4239
3	0.3491	0.3445	0.3445
4	0.3071	0.3042	0.3038
5	0.2669	0.2618	0.2618
6	0.2371	0.2326	0.2326
7	0.2158	0.2090	0.2090
8	0.1993	0.1937	0.1875

Table 2: 3D Star Discrepancy Comparison for $N = 1 \dots 8$ between MPMC (Message-Passing Monte Carlo), LLM evolutionary search, and Clément et al. (provably optimal).

D	S	A	M_i
4	3	1	1 3 5
5	3	2	1 3 7
6	4	1	1 1 3 7

Table 3: Sobol' direction number parameters updated by LLM evolutionary search. D is the dimension, S is the polynomial degree, A is the polynomial's coefficients, and M_i are the initial direction numbers. All other dimensions remained unchanged.

a substantial improvement over the previous best of 0.0188. We generated 2D point sets up to $N = 1020$ with lower star discrepancy than previously reported (Appendix A).

In 3D, our method matched the known optimal point sets for $N = 1, 2, 3, 5, 6, 7$ (Table 2) and provided the first

known explicit low-discrepancy constructions for $N > 8$, establishing new benchmarks (Appendix A).

Improved Direction Numbers for rQMC Integration

Having demonstrated the framework's ability to construct point sets, we next applied it to the discrete optimization problem of discovering improved Sobol' direction numbers.

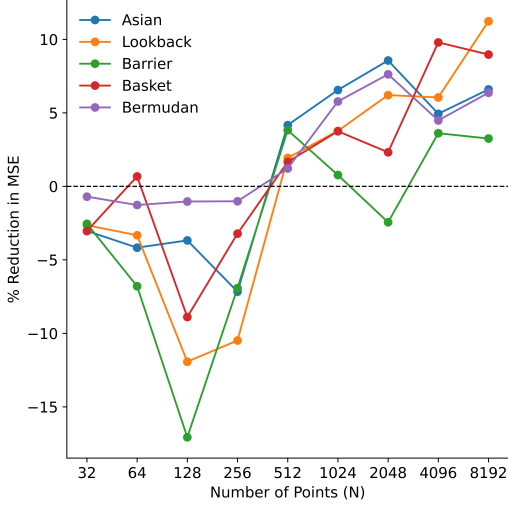


Figure 3: The % reduction in MSE (rQMC integration over 10000 random scrambles and shifts) using Sobol’ direction numbers found via LLM evolutionary search vs. those of Joe and Kuo (2008). The % reduction in MSE are averaged across all scenarios of that particular option (Appendix C).

Scenario	S_0	K	σ	S_{true}
Training Example	50.00	45.00	0.3	7.06
Out-of-the-Money	50.00	60.00	0.3	1.02
At-the-Money	50.00	52.50	0.3	2.98
In-the-Money	50.00	40.00	0.3	11.02
High Volatility	50.00	52.50	0.6	6.43
Low Volatility	50.00	52.50	0.1	0.69

Table 4: Asian Option scenarios used for testing. The Training Example was used in the evaluation routine of the evolutionary search. All options have $T=1.0$ and $r=0.05$.

After several hundred evolutionary iterations, our LLM evolutionary search routine discovered a more performant set of parameters, focusing its modifications on the early dimensions, which are known to explain the vast majority of the variance in Asian option pricing. Specifically, the parameters for dimensions 4, 5, and 6 were updated (Table 3). All other dimensions (up to 32) remained identical to the Joe and Kuo (2008) baseline.

To validate these new direction numbers, they were benchmarked against the standard Joe and Kuo (2008) parameters across a suite of six Asian option pricing scenarios with varying parameters (Table 4). The true option price was computed by taking the average of 1000 randomly scrambled Sobol sequences with $N = 2^{21}$ points each. The rQMC MSE was evaluated over 10000 random seeds for $N = 32 \dots 8192$ points. The direction numbers discovered by LLM evolutionary search produced a significantly lower integration MSE for larger sample sizes $N \geq 512$ under one-sided Wilcoxon rank sum test with false discovery rate correction (Table 5).

To ensure the evolved parameters were not merely overfit-

Listing 4: Iteratively Optimized 2D Point Set ($N = 16$)

```

1 def construct_star():
2     x = np.zeros((N, 2))
3     for i in range(N):
4         x[i, 0] = (i + np.random.rand())
5             / N
6         x[i, 1] = ((i * 0.38196601125) %
7             1) + np.random.rand() / (2*N)
8     def discrepancy_wrapper(x):
9         points = x.reshape(N, 2)
10        return star_discrepancy(points)
11    x0 = x.flatten()
12    bounds = [(0.0, 1.0)] * (N * 2)
13    best_result = None
14    best_discrepancy = float('inf')
15    for _ in range(25):
16        x0_restart = x.flatten() + np.
17            random.normal(0, 0.01, N * 2)
18        x0_restart = np.clip(x0_restart,
19            0.0, 1.0)
20        result = minimize(
21            discrepancy_wrapper,
22            x0_restart, method='SLSQP',
23            bounds=bounds, options={'
24                maxiter': 30000, 'ftol': 1e
25                -15, 'iprint': 0})
26        discrepancy =
27            discrepancy_wrapper(result.x)
28        if discrepancy <
29            best_discrepancy:
30                best_discrepancy =
31                    discrepancy
32                best_result = result
33    optimized_points = best_result.x.
34        reshape(N, 2)
35    return optimized_points

```

ted to the Asian option’s specific payoff structure, we tested their generalizability on a diverse suite of high-dimensional exotic options, including Lookback, Barrier, Basket, and Bermudan options (Appendices C, D). The evolved direction numbers demonstrated strong, generalizable performance, achieving significantly lower integration error across this wider range of financial instruments for larger sample sizes ($N \geq 512$) with the sole exception of Barrier options. This suggests that the evolutionary search discovered a Sobol’ sequence with fundamentally more robust and broadly applicable projection properties.

Discussion

Using an LLM evolutionary framework, we generate 2D and 3D point sets with state-of-the-art star discrepancy and discover Sobol’ direction numbers that lower rQMC integration error for high-dimensional exotic financial option pricing.

Recent state-of-the-art methods, such as the mathematical programming approach of Clément et al. (2024) and the GNN-based MPMC framework (Rusch et al. 2024), are designed to construct point sets for a fixed number of points N and dimensions d . In contrast, our approach generates the direction numbers that define a Sobol’ sequence, offering

N	Training Example			Out-of-the-Money			At-the-Money		
	Sobol	LLM	p-value	Sobol	LLM	p-value	Sobol	LLM	p-value
32	0.2484	0.2523	0.9757	0.1920	0.1979	0.9757	0.3246	0.3346	0.9757
64	0.0642	0.0665	0.9980	0.0605	0.0631	0.9980	0.0873	0.0908	0.9980
128	0.0183	0.0192	0.9999	0.0220	0.0231	0.9999	0.0277	0.0282	0.9999
256	0.0056	0.0061	1.0000	0.0086	0.0089	1.0000	0.0092	0.0098	1.0000
512	0.001646	0.001614	0.2841	0.003469	0.003311	0.0208	0.003248	0.003106	0.0208
1024	0.000542	0.000524	0.0548	0.001457	0.001313	3.45e-08	0.001228	0.001168	0.0304
2048	0.000233	0.000225	0.0199	0.000619	0.000535	1.45e-14	0.000550	0.000521	0.0131
4096	9.876e-05	9.346e-05	0.0058	0.000258	0.000243	4.51e-04	0.000240	0.000226	0.0019
8192	4.523e-05	4.104e-05	7.03e-06	0.000117	0.000107	1.06e-06	0.000102	9.523e-05	0.0100

N	In-the-Money			High Volatility			Low Volatility		
	Sobol	LLM	p-value	Sobol	LLM	p-value	Sobol	LLM	p-value
32	0.1398	0.1428	0.9757	2.0816	2.1493	0.9757	0.0238	0.0246	0.9757
64	0.0367	0.0382	0.9980	0.5714	0.5958	0.9980	0.0066	0.0068	0.9980
128	0.0106	0.0111	0.9999	0.1811	0.1877	0.9999	0.002174	0.002205	0.9999
256	0.003083	0.003373	1.0000	0.0598	0.0643	1.0000	0.000756	0.000803	1.0000
512	0.000868	0.000859	0.2841	0.0205	0.0196	0.0073	0.000285	0.000275	0.0208
1024	0.000261	0.000260	0.2581	0.007565	0.007060	3.38e-04	0.000113	0.000109	0.0717
2048	0.000101	0.000100	0.3878	0.003145	0.002867	1.75e-06	5.214e-05	4.961e-05	0.0056
4096	4.037e-05	3.949e-05	0.2180	0.001293	0.001233	0.0022	2.323e-05	2.196e-05	5.68e-04
8192	1.766e-05	1.683e-05	0.0047	0.000566	0.000532	0.0156	1.008e-05	9.300e-06	1.27e-04

Table 5: Mean Squared Error (MSE) and p-values for Asian Option scenarios. The table compares the standard Sobol’ sequence against a sequence found via LLM evolutionary search (LLM). P-values are from a one-sided Wilcoxon signed-rank test conducted over the 10000 randomizations and are false discovery rate (FDR) corrected. P-values below 0.05 are **bolded**.

several key advantages:

1. **Extensibility to any N:** Unlike fixed approaches where a new, computationally expensive optimization must be performed from scratch for each value of N , a single, compact set of discovered direction numbers can be used to generate a high-quality point set for any desired number of points. This makes the solution immediately applicable to a wide range of practical problems without requiring any re-computation.
2. **Support for Progressive Integration:** An integration can be performed with N points, and if more accuracy is needed, the next N points from the sequence can be added to refine the estimate while reusing all previous calculations. This is a fundamental capability that static point set generation methods inherently lack.
3. **Easy Randomization:** Unlike highly optimized, deterministic point sets, the LLM optimized Sobol’ sequence can make use of standard randomization techniques, such as Owen scrambling (Owen 1995, 1998), to obtain unbiased error estimates of rQMC.
4. **High-Dimensional Applicability:** The Sobol’ framework is designed from the ground up for high-dimensional integration. By optimizing the parameters within this framework, our approach is directly applicable to problems such as the 32-dimensional option pricing benchmarks used in our tests, a domain where direct coordinate optimization for a large N would be computationally intractable.

It is notable that the performance gains from the LLM-evolved Sobol’ parameters did not extend to the pricing of Barrier options (Appendix D). We hypothesize that this is a

direct consequence of our fitness function, which was optimized for the integration of a 32-dimensional Asian option. The payoff of an Asian option is dependent on the average of the asset path, resulting in a comparatively smooth and continuous integrand. In contrast, the payoff of a Barrier option contains a significant discontinuity, which poses a well-known challenge for QMC integration by introducing high or even unbounded Hardy-Krause variation.

Our evolutionary search likely discovered parameters that are highly specialized for integrating functions of low-to-moderate variation, a property that does not generalize well to discontinuous integrands. This suggests that the notion of an ‘optimal’ Sobol’ sequence may be problem-dependent. Future work could explore multi-objective optimization, where the fitness function is a composite score from pricing both smooth (e.g. Asian) and discontinuous (e.g. Barrier) options. Such an approach might lead to the discovery of more robust, universally applicable direction numbers at the potential cost of peak performance on any single problem class.

Other limitations include the computational intensity of the evolutionary search that must be run independently for each specific case. In addition, the quality of the generated solutions is also fundamentally tied to the capabilities of the underlying LLM and the amount of compute available. Future work could explore alternative prompting techniques, optimization of evolutionary programming hyperparameters, and meta-model methods that generates optimal direction numbers for any given dimension d or points sets for any given dimension d or number of points N .

Conclusion

We have demonstrated the application of an LLM-driven evolutionary framework to tackle complex discovery problems in the field of low-discrepancy sets. Our method has discovered new 2D and 3D point sets with star discrepancy values lower than any previously published, setting new benchmarks in a field of long-standing mathematical interest. Furthermore, it has produced novel Sobol direction numbers that improve the accuracy of rQMC integration for a variety of 32-dimensional financial derivatives. This work strengthens the case for using LLMs as core components in an automated scientific discovery process, capable of generating novel and valuable mathematical knowledge.

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Appendix

This appendix provides the full numerical results for the star discrepancy (D_N^*) values of the point sets discovered by LLM evolutionary search. These tables serve as a comprehensive record of the performance of our method, establishing new state-of-the-art benchmarks and offering a detailed comparison against established low-discrepancy construction methods.

New Benchmarks in Three Dimensions

We report high-quality constructions for N from 9 to 16 (Table 6).

Performance in Two Dimensions for $N \geq 140$

In two dimensions, while the problem is better understood than in 3D, optimal solutions for larger point sets ($N > 21$) are not known. We provide a detailed comparison of the 2D star discrepancy values achieved by LLM evolutionary optimization against several key baselines for N ranging from 140 to 1020 (Table 7).

- **Consistent Outperformance:** Across every single value of N tested, the point sets discovered by LLM evolutionary search achieve a lower star discrepancy than all other methods, including classical sequences (Halton, Sobol', Hammersley, Fibonacci) and the recent state-of-the-art MPMC method.
- **Significant Improvement Margin:** The performance gap is not trivial. For example, at $N = 140$, the LLM discrepancy of 0.01151 is approximately 16% lower than the next-best method (MPMC at 0.01373) and over 57% lower than the widely used Halton sequence. At $N = 1020$, the LLM discrepancy of 0.00245 is nearly 20% better than MPMC's 0.00303.
- **Superior Scaling:** The results demonstrate that the LLM evolutionary search's ability to find superior configurations is not limited to a specific range of N , but holds consistently as the number of points increases. This suggests that the two-phase discovery strategy (direct construction followed by iterative optimization) is effective at navigating the increasingly complex search space associated with larger point sets.

N	LLM Discrepancy (D_N^*)
9	0.1758
10	0.1652
11	0.1551
12	0.1483
13	0.1402
14	0.1337
15	0.1275
16	0.1207

Table 6: The Star Discrepancy Values for $N > 8$ 3D point sets found via LLM evolutionary search.

LLM Prompts

This appendix provides the full instructional text of the prompts provided to the Large Language Model (LLM) within the OpenEvolve framework. These LLM prompts were used to generate programs to construct point sets directly (Fig. 4), iteratively optimize point sets (Fig. 5), and directly construct Sobol' direction numbers (Fig. 6).

It is important to note that the text shown in the figures below constitutes the instructional component of a larger prompt. This text is dynamically combined with the source code of a "parent" program selected for mutation and often includes code from other high-performing "inspiration" programs to encourage crossover of ideas.

Option Scenarios

To ensure a rigorous evaluation of the Sobol' direction numbers discovered, we designed a comprehensive suite of benchmark scenarios. This suite includes the primary optimization target (the Asian option) as well as a diverse set of exotic options known to be challenging for Quasi-Monte Carlo integration. The purpose of this suite is twofold: first, to confirm superior performance on the target problem class, and second, to test for generalizability and ensure that the evolved parameters were not merely overfitted to the specific payoff structure of the Asian option.

The configuration parameters for all tested scenarios are consolidated in (Table 8). For all options, the time to expiration (T) was set to 1.0 year and the risk-free interest rate (r) was 0.05. The underlying asset prices are assumed to follow a geometric Brownian motion.

Asian Options

An Asian option is a path-dependent exotic option whose payoff is determined by the average price of the underlying asset over a pre-set period of time. This is in contrast to a standard European option, which only depends on the asset price at expiration. The averaging feature reduces volatility and makes the option generally cheaper than its European counterpart. Because its value depends on the entire price path, pricing it requires simulating all 32 time steps, making it an excellent candidate for QMC methods.

Lookback Options

A lookback option is another path-dependent option whose payoff is determined by the maximum or minimum price of the underlying asset over the option's life. The scenarios tested here are for a floating strike lookback call option, whose payoff at expiration is the difference between the final asset price and the minimum price achieved ($S_T - S_{min}$).

Barrier Options

A barrier option is a path-dependent option that is either activated ("knocks-in") or extinguished ("knocks-out") if the underlying asset price crosses a predetermined "barrier" level. This feature introduces a significant discontinuity in the payoff function.

N	Halton	Sobol'	Hammersley	Fibonacci	MPMC	LLM
140	0.03686	0.02794	0.02701	0.01870	0.01373	0.01151
180	0.03200	0.02300	0.02283	0.01454	0.01147	0.01058
220	0.02323	0.01924	0.01868	0.01190	0.00975	0.00891
260	0.02062	0.01546	0.01581	0.01063	0.00843	0.00831
300	0.01994	0.01341	0.01424	0.00972	0.00752	0.00741
340	0.01950	0.01353	0.01266	0.00858	0.00710	0.00696
380	0.01659	0.01167	0.01170	0.00768	0.00695	0.00638
420	0.01617	0.01194	0.01058	0.00694	0.00584	0.00563
460	0.01279	0.00972	0.00966	0.00634	0.00540	0.00471
500	0.01172	0.00848	0.00889	0.00583	0.00518	0.00509
540	0.01101	0.00967	0.00823	0.00540	0.00488	0.00407
580	0.01261	0.00956	0.00766	0.00503	0.00476	0.00377
620	0.01140	0.00782	0.00744	0.00470	0.00454	0.00386
660	0.01074	0.00956	0.00699	0.00463	0.00437	0.00360
700	0.00933	0.00865	0.00682	0.00437	0.00416	0.00379
740	0.00891	0.00709	0.00646	0.00435	0.00397	0.00346
780	0.00870	0.00662	0.00612	0.00412	0.00376	0.00310
820	0.00881	0.00678	0.00583	0.00392	0.00360	0.00294
860	0.00914	0.00604	0.00556	0.00374	0.00356	0.00316
900	0.00751	0.00561	0.00531	0.00357	0.00319	0.00296
940	0.00785	0.00481	0.00508	0.00342	0.00321	0.00289
980	0.00768	0.00558	0.00487	0.00328	0.00308	0.00280
1020	0.00777	0.00395	0.00468	0.00315	0.00303	0.00245

Table 7: 2D Star Discrepancy Comparison for $N \geq 140$. This table compares the performance of LLM evolutionary search against classical low-discrepancy sequences and the state-of-the-art MPMC method for larger point sets where optimal solutions are not known. Lower values indicate better uniformity. The best result in each row is **bolded**.

Basket Options

A basket option's payoff depends on the value of a portfolio or "basket" of multiple underlying assets. It is an inherently high-dimensional problem where the correlation (ρ) between the assets is a critical parameter. For these tests, we assume a uniform initial price of $S_0 = 100.00$ for all 32 assets in the basket.

Bermudan Options

A Bermudan option is a hybrid between a European option (exercisable only at expiration) and an American option (exercisable at any time). It can be exercised on a discrete set of pre-specified dates. Pricing a Bermudan option is a highly complex problem that requires solving a dynamic programming problem to determine the optimal exercise strategy.

RQMC Integration Results

This appendix provides the detailed results for the primary benchmark (Asian Option) and the generalizability tests (exotic options). Each table compares the performance of the standard Sobol' sequence (Joe & Kuo) against the direction numbers discovered by LLM evolutionary search. We report the Mean Squared Error (MSE) and its constituent parts, Squared Bias and Variance, for an increasing number of points (N). We consistently found lower variance and MSE for all options types for all $N \geq 512$ with two exceptions: close barrier option ($N = 2048$) and a high correlation basket option ($N = 2048$).

LLM Prompt for Direct Construction

You are an expert mathematician specializing in the construction of QMC sampling points in a square. Your task is to improve a constructor function that directly outputs the position of 16 points on a unit square $([0, 1] \times [0, 1])$ in a way that minimizes the star discrepancy.

The star discrepancy is a measure of how uniformly distributed the points are in the square. It is defined as the supremum of the absolute value of the difference between the fraction of points and the area.

Focus on designing an explicit constructor that specifies the position of each point (x, y) in the unit square, rather than an iterative search algorithm. It should output the position of each point (x, y) in the square $[0, 1] \times [0, 1]$. 0.0 and 1.0 are included in the square.

Figure 4: The full prompt provided to the LLM for generating programs that directly construct point sets with minimum star discrepancy.

LLM Prompt for Iterative Optimization

You are an expert mathematician specializing in the construction of QMC sampling points in a 2D square. Your task is to improve a constructor function that finds the position of 16 points on a unit square $([0, 1] \times [0, 1])$ in a way that minimizes the star discrepancy.

The star discrepancy is a measure of how uniformly distributed the points are in the square. It is defined as the supremum of the absolute value of the difference between the fraction of points and the area.

Use scipy optimization routines such as `scipy.optimize.minimize` to fine-tune the construction. The optimization routine and its initialization is critically important.

It should output the position of each point (x, y) in the square $[0, 1] \times [0, 1]$. 0.0 and 1.0 are included in the square.

Figure 5: The full prompt provided to the LLM for generating programs that iteratively optimize point sets to have minimum star discrepancy.

Option Type	Scenario	Initial Price (S_0)	Strike Price (K)	Volatility (σ)	Other Parameters
Asian	Training Example	50.00	45.00	0.3	—
	Out-of-the-Money	50.00	60.00	0.3	—
	At-the-Money	50.00	52.50	0.3	—
	In-the-Money	50.00	40.00	0.3	—
	High Volatility	50.00	52.50	0.6	—
Lookback	Low Volatility	50.00	52.50	0.1	—
	Base	100.00	—	0.2	—
Barrier	High Volatility	100.00	—	0.4	—
	Base	100.00	100.00	0.2	Barrier Level: 85.00
Basket (32D)	Close Barrier	100.00	100.00	0.2	Barrier Level: 95.00
	Low Correlation	—	100.00	0.2	ρ : 0.1
	High Correlation	100.00	100.00	0.2	ρ : 0.8
	Mixed Volatility	100.00	100.00	$U(0.15, 0.4)$	ρ : 0.5
Bermudan	Out-of-the-Money	100.00	110.00	0.2	ρ : 0.1
	At-the-Money	100.00	100.00	0.2	Exercise Dates: 4
	In-the-Money	90.00	100.00	0.2	Exercise Dates: 4

Table 8: Configuration Parameters for All Tested Option Scenarios. This table details the parameters for the 32-dimensional options used in the primary benchmark and generalizability tests. For all scenarios, the time to expiration (T) is 1.0 year and the risk-free interest rate (r) is 0.05. An em-dash (—) indicates a parameter is not applicable to that option type.

LLM Prompt for Sobol' Direction Numbers Search

You are an expert mathematician specializing in the construction of QMC sampling points in a square. Your task is to improve a constructor function that directly outputs the direction numbers for dimensions 2 to 32 of a Sobol Sequence.

Your goal is to minimize the approximation error of a 32 dimensional asian option price. The dimensions 1, 2, and 3 explain roughly 97% of the variance of the price.

The Sobol sequence is defined by a polynomial of degree s , with coefficients represented as an integer a , and direction numbers m_i for each dimension i . The direction numbers must be odd integers and within the specified range.

You must return a list of 31 dictionaries for directions 2 to 32, each containing the following keys:

- "s" (int): The degree of the polynomial. $1 \leq s \leq 30$
- "a" (int): The coefficients of the polynomial, represented as an integer. $0 \leq a < 2^{s-1}$
- "m_i" (list[int]): The direction numbers for the Sobol sequence, represented as a list of integers of length s . Each integer should be in the range $[0, 2^{i+1}]$ and has to be odd.

Focus on designing an explicit constructor that specifies these parameters, rather than an iterative search algorithm.

Figure 6: The full prompt provided to the LLM for generating a program that directly specifies Sobol' direction numbers to have lower integration error for an Asian Option.

Scenario	N	Squared Bias		Variance		MSE		p-value
		Sobol	LLM	Sobol	LLM	Sobol	LLM	
Training Example	32	2.09e-05	5.59e-07	0.2484	0.2523	0.2484	0.2523	0.9757
	64	5.37e-06	9.58e-06	0.0642	0.0665	0.0642	0.0665	0.9980
	128	5.10e-06	4.96e-06	0.0183	0.0192	0.0183	0.0192	0.9999
	256	2.87e-07	1.43e-07	0.0056	0.0061	0.0056	0.0061	1.0000
	512	6.09e-08	3.51e-09	0.001646	0.001614	0.001646	0.001614	0.2841
	1024	7.89e-08	1.33e-08	0.000542	0.000524	0.000542	0.000524	0.0548
	2048	2.60e-08	2.30e-12	0.000233	0.000225	0.000233	0.000225	0.0199
	4096	9.11e-10	3.46e-09	9.876e-05	9.346e-05	9.876e-05	9.346e-05	0.0058
Out-of-the-Money	8192	1.55e-09	1.93e-10	4.523e-05	4.104e-05	4.523e-05	4.104e-05	7.03e-06
	32	3.73e-05	6.41e-07	0.1920	0.1979	0.1920	0.1979	0.9757
	64	1.48e-06	9.78e-09	0.0605	0.0631	0.0605	0.0631	0.9980
	128	3.74e-07	1.66e-06	0.0220	0.0231	0.0220	0.0231	0.9999
	256	3.07e-07	2.60e-07	0.0086	0.0089	0.0086	0.0089	1.0000
	512	4.47e-08	4.05e-11	0.003469	0.003311	0.003469	0.003311	0.0208
	1024	1.29e-08	4.45e-08	0.001457	0.001313	0.001457	0.001313	3.45e-08
	2048	2.92e-11	3.36e-08	0.000619	0.000535	0.000619	0.000535	1.45e-14
At-the-Money	4096	5.09e-08	1.17e-09	0.000258	0.000243	0.000258	0.000243	4.51e-04
	8192	3.71e-09	3.24e-09	0.000117	0.000107	0.000117	0.000107	1.06e-06
	32	5.90e-05	1.35e-09	0.3246	0.3346	0.3246	0.3346	0.9757
	64	1.35e-05	1.17e-05	0.0873	0.0908	0.0873	0.0908	0.9980
	128	9.72e-06	1.45e-06	0.0277	0.0282	0.0277	0.0282	0.9999
	256	1.12e-06	2.06e-08	0.0092	0.0098	0.0092	0.0098	1.0000
	512	1.83e-08	5.57e-10	0.003248	0.003106	0.003248	0.003106	0.0208
	1024	3.60e-08	4.58e-09	0.001228	0.001168	0.001228	0.001168	0.0304
In-the-Money	2048	7.85e-11	1.82e-08	0.000550	0.000521	0.000550	0.000521	0.0131
	4096	3.16e-10	8.98e-10	0.000240	0.000226	0.000240	0.000226	0.0019
	8192	7.47e-09	3.31e-09	0.000102	9.522e-05	0.000102	9.523e-05	0.0100
	32	1.93e-05	3.11e-09	0.1397	0.1428	0.1398	0.1428	0.9757
	64	2.30e-06	2.86e-06	0.0367	0.0382	0.0367	0.0382	0.9980
	128	1.67e-06	1.74e-06	0.0106	0.0111	0.0106	0.0111	0.9999
	256	1.08e-09	3.54e-08	0.003083	0.003373	0.003083	0.003373	1.0000
	512	3.07e-10	4.26e-08	0.000868	0.000859	0.000868	0.000859	0.2841
High Volatility	1024	1.53e-09	6.44e-10	0.000261	0.000260	0.000261	0.000260	0.2581
	2048	3.54e-10	1.28e-08	0.000101	0.000100	0.000101	0.000100	0.3878
	4096	2.15e-11	3.38e-09	4.037e-05	3.949e-05	4.037e-05	3.949e-05	0.2180
	8192	2.77e-10	3.70e-09	1.766e-05	1.682e-05	1.766e-05	1.683e-05	0.0047
	32	0.000333	2.83e-07	2.0813	2.1493	2.0816	2.1493	0.9757
	64	5.87e-05	4.32e-05	0.5713	0.5958	0.5714	0.5958	0.9980
	128	4.41e-05	5.25e-06	0.1810	0.1877	0.1811	0.1877	0.9999
	256	1.78e-06	1.90e-06	0.0598	0.0643	0.0598	0.0643	1.0000
Low Volatility	512	2.34e-09	1.49e-08	0.0205	0.0196	0.0205	0.0196	0.0073
	1024	1.21e-07	2.19e-07	0.007565	0.007060	0.007565	0.007060	3.38e-04
	2048	6.34e-08	1.22e-07	0.003145	0.002867	0.003145	0.002867	1.75e-06
	4096	2.93e-10	6.09e-09	0.001293	0.001233	0.001293	0.001233	0.0022
	8192	3.59e-08	4.35e-08	0.000566	0.000532	0.000566	0.000532	0.0156
	32	5.75e-06	1.26e-08	0.0238	0.0246	0.0238	0.0246	0.9757
	64	1.28e-06	6.48e-07	0.0066	0.0068	0.0066	0.0068	0.9980
	128	7.71e-07	2.71e-08	0.002173	0.002205	0.002174	0.002205	0.9999
Low Volatility	256	1.08e-07	1.12e-08	0.000756	0.000803	0.000756	0.000803	1.0000
	512	6.51e-09	1.55e-09	0.000285	0.000275	0.000285	0.000275	0.0208
	1024	5.18e-09	1.20e-09	0.000113	0.000109	0.000113	0.000109	0.0717
	2048	2.66e-10	2.17e-09	5.214e-05	4.961e-05	5.214e-05	4.961e-05	0.0056
	4096	1.26e-10	1.39e-10	2.323e-05	2.196e-05	2.323e-05	2.196e-05	5.68e-04
	8192	3.43e-10	3.09e-10	1.008e-05	9.300e-06	1.008e-05	9.300e-06	1.27e-04

Table 9: Integration results for the Asian Option across all six scenarios. The table compares the standard Sobol' sequence (Joe & Kuo) against the direction numbers discovered by LLM evolutionary search. We report the Mean Squared Error (MSE), its constituent parts (Squared Bias and Variance), and the FDR-corrected p-value from a one-sided Wilcoxon signed-rank test. P-values below 0.05 and the best methods are **bolded**.

Scenario	N	Squared Bias		Variance		MSE		p-value
		Sobol	LLM	Sobol	LLM	Sobol	LLM	
Base	32	3.90e-06	8.56e-05	1.2138	1.2443	1.2138	1.2444	0.9968
	64	4.16e-06	3.01e-05	0.4725	0.4839	0.4725	0.4840	1.0000
	128	3.14e-06	2.35e-07	0.1272	0.1352	0.1272	0.1352	1.0000
	256	1.61e-06	4.90e-06	0.0352	0.0381	0.0352	0.0381	1.0000
	512	8.86e-07	1.10e-06	0.0121	0.0120	0.0121	0.0120	0.4675
	1024	9.64e-07	1.43e-06	0.005021	0.004905	0.005022	0.004907	0.0342
	2048	6.88e-08	1.29e-07	0.001834	0.001744	0.001834	0.001744	4.13e-04
	4096	1.32e-07	5.59e-08	0.000807	0.000768	0.000807	0.000768	2.38e-04
High Volatility	8192	5.21e-08	3.61e-08	0.000407	0.000377	0.000407	0.000377	9.84e-09
	32	2.13e-04	4.44e-04	8.5591	8.7869	8.5593	8.7873	0.9968
	64	6.04e-08	1.16e-04	3.3964	3.5134	3.3964	3.5136	1.0000
	128	2.87e-05	2.57e-06	0.8854	0.9982	0.8854	0.9982	1.0000
	256	3.14e-06	1.46e-05	0.2403	0.2663	0.2403	0.2663	1.0000
	512	7.96e-07	1.11e-07	0.0809	0.0792	0.0809	0.0792	0.3836
	1024	2.57e-06	7.04e-06	0.0325	0.0312	0.0325	0.0312	6.24e-04
	2048	3.37e-07	4.92e-08	0.012003	0.011234	0.012003	0.011234	2.26e-06
	4096	1.47e-07	2.32e-08	0.004862	0.004558	0.004862	0.004558	2.65e-06
	8192	2.12e-10	6.25e-09	0.002335	0.002057	0.002335	0.002057	9.79e-17

Table 10: Integration results for the Lookback Option across two scenarios. We report FDR-corrected P-values from a one-sided Wilcoxon signed-rank test. P-values below 0.05 and the best methods are **bolded**.

Scenario	N	Squared Bias		Variance		MSE		p-value
		Sobol	LLM	Sobol	LLM	Sobol	LLM	
Base	32	1.13e-04	2.87e-05	2.2540	2.3339	2.2541	2.3339	0.9968
	64	2.17e-05	4.56e-06	0.8386	0.8894	0.8386	0.8894	1.0000
	128	2.32e-05	2.37e-05	0.2533	0.3101	0.2534	0.3101	1.0000
	256	1.97e-06	7.40e-06	0.0707	0.0834	0.0707	0.0834	1.0000
	512	5.72e-07	4.84e-06	0.0245	0.0241	0.0245	0.0241	0.4675
	1024	7.63e-07	7.40e-07	0.009948	0.009819	0.009948	0.009819	0.3313
	2048	4.03e-07	1.12e-06	0.004277	0.004230	0.004277	0.004231	0.3025
	4096	8.61e-08	1.00e-07	0.002019	0.001992	0.002019	0.001992	0.3863
Close Barrier	8192	1.82e-08	5.70e-08	0.000985	0.000955	0.000985	0.000955	0.0859
	32	9.55e-04	1.27e-04	3.2150	3.2754	3.2160	3.2755	0.9968
	64	6.55e-05	1.44e-05	1.1229	1.2054	1.1229	1.2054	1.0000
	128	5.52e-05	1.14e-05	0.4541	0.5183	0.4542	0.5183	1.0000
	256	3.62e-05	8.39e-07	0.1733	0.1775	0.1733	0.1775	1.0000
	512	3.76e-05	7.16e-07	0.0723	0.0690	0.0723	0.0690	0.2364
	1024	2.27e-05	2.62e-06	0.0328	0.0326	0.0328	0.0326	0.4459
	2048	1.52e-06	1.13e-09	0.01594	0.01648	0.01594	0.01648	0.9126
	4096	3.83e-07	4.25e-07	0.007027	0.006727	0.007028	0.006728	0.0574
	8192	3.48e-09	3.79e-07	0.003379	0.003266	0.003379	0.003267	0.1613

Table 11: Integration results for the Barrier Option across two scenarios. We report FDR-corrected p-values from a one-sided Wilcoxon signed-rank test. P-values below 0.05 and the best methods are **bolded**.

Scenario	N	Squared Bias		Variance		MSE		p-value
		Sobol	LLM	Sobol	LLM	Sobol	LLM	
Low Correlation	32	3.82e-06	5.13e-07	0.1152	0.1182	0.1152	0.1182	0.9968
	64	6.60e-07	1.99e-06	0.0342	0.0358	0.0342	0.0358	1.0000
	128	1.18e-06	1.38e-06	0.0109	0.0126	0.0109	0.0126	1.0000
	256	5.16e-08	1.38e-08	0.0036	0.0039	0.0036	0.0039	1.0000
	512	3.04e-07	1.15e-08	0.001259	0.001231	0.001259	0.001231	0.2381
	1024	2.00e-07	1.79e-08	0.000504	0.000473	0.000504	0.000473	0.0051
	2048	5.00e-08	6.46e-11	0.000229	0.000214	0.000229	0.000214	3.79e-04
	4096	1.12e-10	1.32e-09	9.886e-05	9.038e-05	9.886e-05	9.038e-05	1.68e-04
High Correlation	8192	1.39e-09	1.72e-10	4.740e-05	4.157e-05	4.740e-05	4.157e-05	1.92e-11
	32	9.26e-05	9.80e-05	0.2483	0.2557	0.2484	0.2558	0.9968
	64	7.77e-06	1.10e-05	0.0602	0.0570	0.0602	0.0571	2.61e-05
	128	6.94e-06	2.65e-06	0.0163	0.0168	0.0163	0.0168	1.0000
	256	7.96e-07	8.54e-07	0.004907	0.004944	0.004908	0.004945	1.0000
	512	6.53e-08	8.95e-08	0.001527	0.001518	0.001527	0.001518	0.4675
	1024	3.80e-10	1.16e-08	0.000463	0.000447	0.000463	0.000447	0.0784
	2048	3.45e-09	1.57e-09	0.0001750	0.0001779	0.0001750	0.0001779	0.7419
Mixed Volatility	4096	8.68e-10	7.39e-09	7.132e-05	6.609e-05	7.132e-05	6.610e-05	8.20e-04
	8192	6.90e-09	1.17e-10	2.598e-05	2.448e-05	2.599e-05	2.448e-05	5.32e-03
	32	2.19e-04	9.65e-05	0.7753	0.7993	0.7755	0.7994	0.9968
	64	9.78e-06	1.28e-05	0.2098	0.2071	0.2099	0.2071	0.5396
	128	1.95e-05	2.19e-06	0.0647	0.0702	0.0647	0.0702	1.0000
	256	4.42e-06	1.52e-06	0.0211	0.0216	0.0211	0.0216	1.0000
	512	6.51e-07	6.07e-07	0.006202	0.006112	0.006202	0.006112	0.6395
	1024	1.17e-08	5.20e-09	0.002089	0.002026	0.002089	0.002026	0.0784
Out-of-the-Money	2048	1.09e-08	4.65e-11	0.000947	0.000932	0.000947	0.000932	0.0672
	4096	3.40e-09	2.79e-08	0.000447	0.000393	0.000447	0.000393	1.45e-10
	8192	1.80e-08	2.19e-12	0.000156	0.000143	0.000156	0.000143	1.48e-05
	32	2.43e-05	2.29e-09	0.1165	0.1205	0.1166	0.1205	0.9968
	64	2.81e-06	4.90e-09	0.0367	0.0387	0.0367	0.0387	1.0000
	128	2.55e-06	2.01e-07	0.0127	0.0143	0.0127	0.0143	1.0000
	256	5.97e-07	4.26e-10	0.004370	0.004627	0.004371	0.004627	1.0000
	512	2.65e-07	2.67e-08	0.001602	0.001553	0.001602	0.001553	0.2364
	1024	3.70e-08	2.12e-09	0.000652	0.000623	0.000652	0.000623	0.0651
	2048	5.68e-09	3.00e-11	0.000292	0.000281	0.000292	0.000281	0.0856
	4096	1.01e-08	5.67e-09	0.000125	0.000120	0.000125	0.000120	0.0027
	8192	1.58e-11	1.66e-09	5.949e-05	5.392e-05	5.949e-05	5.392e-05	2.53e-06

Table 12: Integration results for the 32-dimensional Basket Option across four scenarios. We report FDR-corrected p-values from a one-sided Wilcoxon signed-rank test. P-values below 0.05 and the best methods are **bolded**.

Scenario	N	Squared Bias		Variance		MSE		p-value
		Sobol	LLM	Sobol	LLM	Sobol	LLM	
At-the-Money	32	0.8165	0.8272	0.5744	0.5826	1.3909	1.4098	0.9968
	64	0.2544	0.2627	0.2403	0.2372	0.4948	0.4999	1.0000
	128	0.0698	0.0725	0.0941	0.0951	0.1639	0.1677	1.0000
	256	0.0182	0.0192	0.0441	0.0445	0.0624	0.0637	1.0000
	512	0.0044	0.0041	0.0218	0.0221	0.02621	0.02622	0.4675
	1024	9.87e-04	9.33e-04	0.0118	0.0112	0.0128	0.0122	0.0115
	2048	2.77e-04	2.46e-04	0.005957	0.005713	0.006234	0.005960	0.0018
	4096	5.23e-05	4.25e-05	0.002696	0.002676	0.002749	0.002718	0.3863
	8192	1.10e-05	8.45e-06	0.001324	0.001273	0.001335	0.001281	0.0457
In-the-Money	32	0.8888	0.8979	0.5629	0.5549	1.4518	1.4528	0.9968
	64	0.2226	0.2296	0.2507	0.2509	0.4733	0.4805	1.0000
	128	0.0478	0.0489	0.1183	0.1169	0.1662	0.1658	1.0000
	256	0.0092	0.0093	0.0564	0.0563	0.0656	0.0656	1.0000
	512	0.0020	0.0019	0.0284	0.0278	0.0304	0.0297	0.4675
	1024	3.75e-04	4.09e-04	0.0145	0.0135	0.0149	0.0139	0.0142
	2048	6.75e-05	7.12e-05	0.007354	0.006584	0.007422	0.006655	1.22e-05
	4096	1.17e-05	9.36e-06	0.003369	0.003128	0.003381	0.003137	7.39e-04
	8192	3.56e-06	3.86e-06	0.001660	0.001523	0.001664	0.001527	1.62e-04

Table 13: Integration results for the Bermudan Option across two scenarios. We report FDR-corrected p-values from a one-sided Wilcoxon signed-rank test. P-values below 0.05 and the best methods are **bolded**.